

# **Operating Systems**

## **BCA –IV th Sem**

### ***Deadlocks***

By

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# Text @ OS notes book

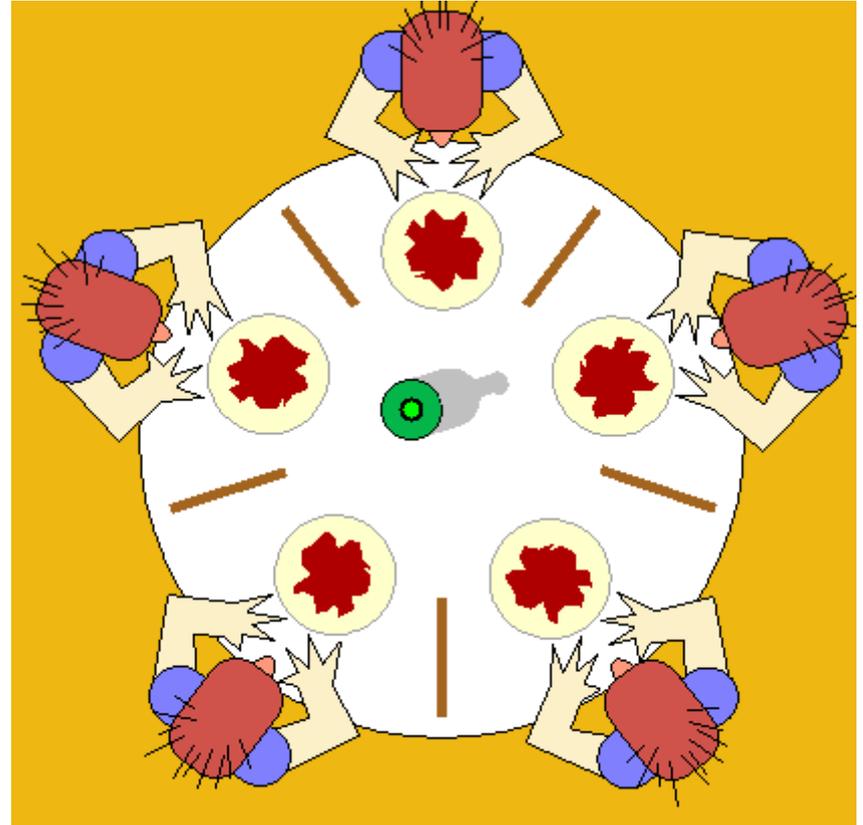
- **Much of the material appears in Section 3.2 in Feitelson's OS notes book**
  - Literature section in course homepage
- **In case this presentation and book conflicts**
  - As always, this presentation wins

# Intro

- **In the previous lecture**
  - We've talked about how to synchronize access to shared resources
- **When synchronizing, if we're not careful**
  - Our system might enter a deadlock state
- **The popular formal CS definition of a dealock**
  - “A set of processes is deadlocked if each process in the set is waiting for an event that only a process in the set can cause”
- **Typically associated with synch-ing the use of resources**
  - Let's revise the definition accordingly
  - A set of processes is deadlocked if each process in the set is waiting for a resource held by another process in the set
- **“The dining philosophers problem”**
  - The canonical example in introductory OS lectures to demonstrate deadlocks

# Dining philosophers – rules

- Five philosophers are sitting around a large round table, each with a bowl of Chinese food in front of him
- Between periods of meditation, they may start eating whenever they want to, with their bowls being filled frequently
- But there are only five chopsticks available, one between every pair of bowls -- and for eating Chinese food, one needs two chopsticks...
- When a philosopher wants to start eating, he must pick up the chopstick to the left of his bowl and the chopstick to the right of his bowl

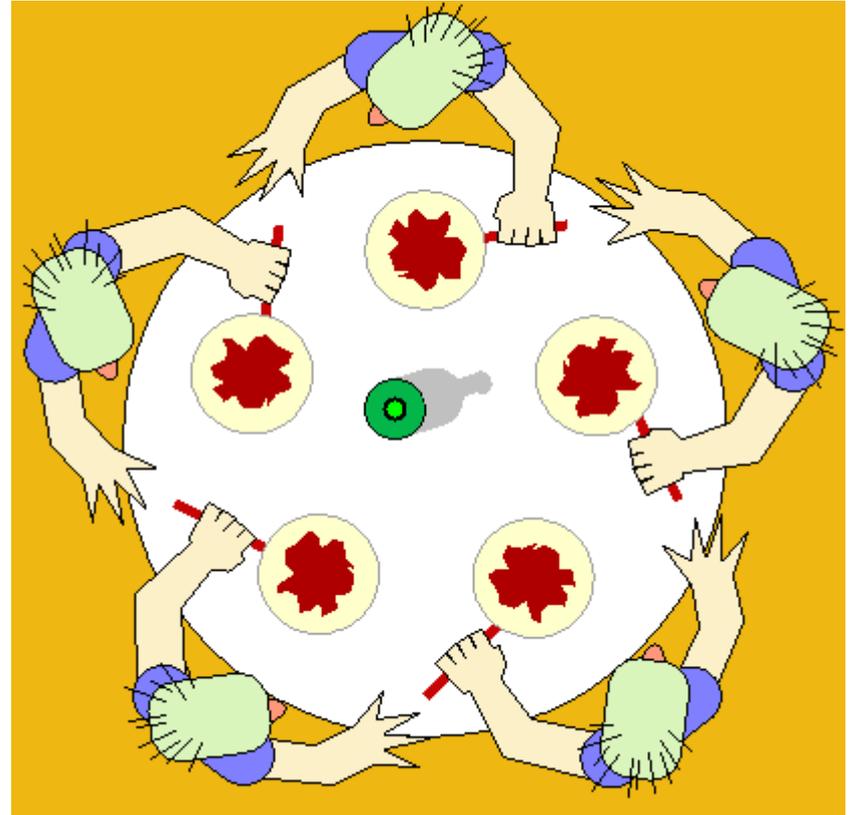


# Dining philosophers – naive solution

- **Semaphore for each fork**
  - semaphore\_t fork[5]
  - (What if forks were placed in the middle of the table and any philosopher would be able to grab any fork? Would we still need 5 semaphores?)
- **Naive (faulty) algorithm**
  - philosopher(i):  
while(1) do...
    - thinking for a while
    - wait( fork[i] )
    - wait( fork[(i+1) % 5] )
    - eat
    - signal( fork[(i+1) % 5] )
    - signal( fork[i] )

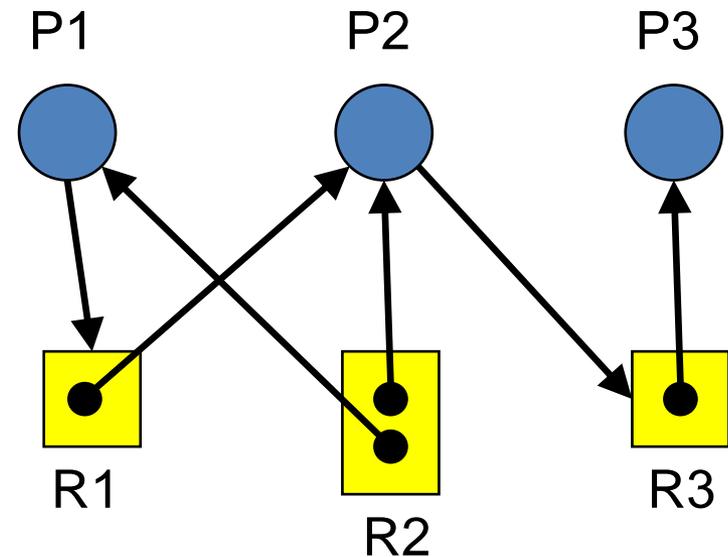
# Dining philosophers – problem

- All the philosophers become hungry at the exact same time
- They simultaneously pick up the chopstick to their left
- They then all try to pick up the chopstick to their right
- Only to find that those chopsticks have already been picked up (by the philosopher on their right)
- The philosophers then continue to sit there indefinitely, each holding onto one fork, glaring at his neighbor angrily
- They are deadlocked



# Resource allocation graph

- **When considering resource management**
  - Convenient to represent system state with a directed graph
- **2 types of nodes**
  - Process = round node
  - Resource type = square node
    - Within resource, each instance = a dot
- **2 types of edges**
  - Request = edge from process to resource type
  - Allocation = edge from resource instance to a process



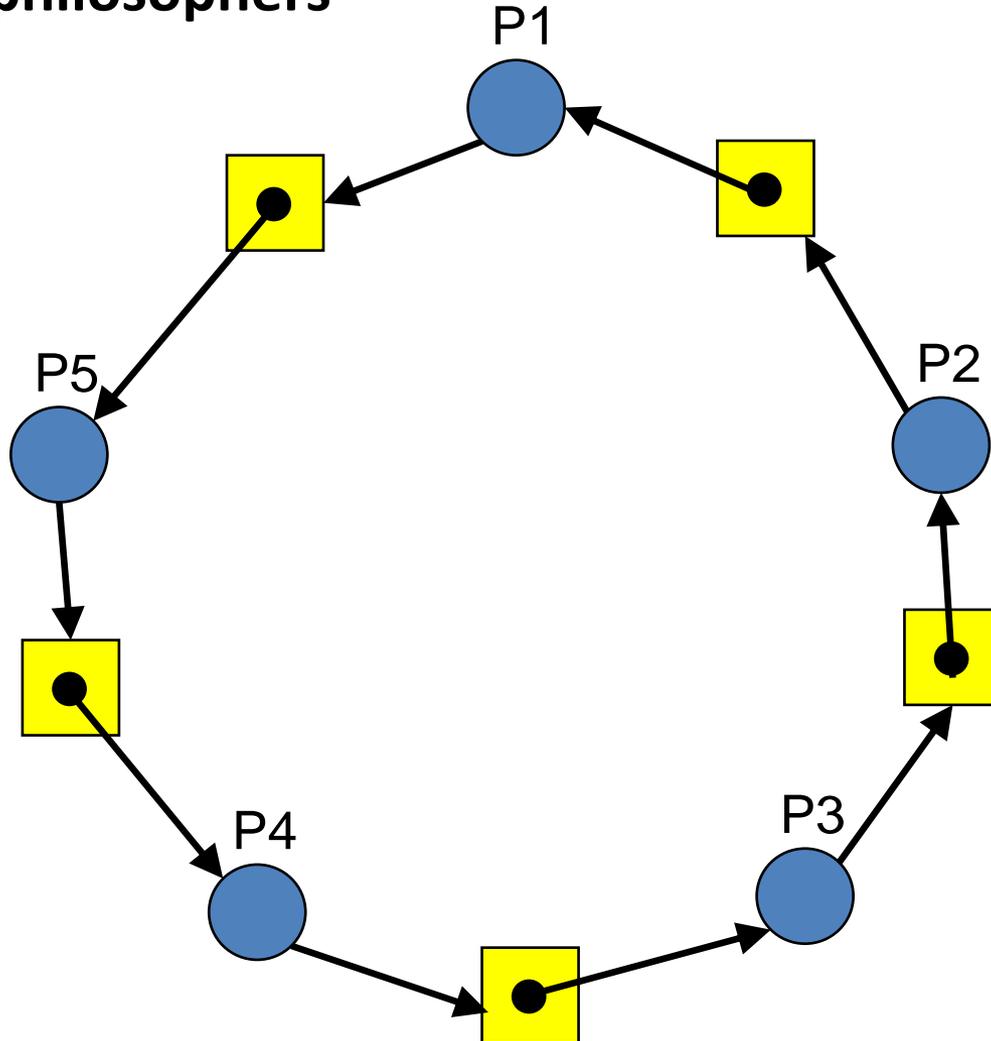
<b>P1</b>	Holds instance of R2. Waits for R1.
<b>P2</b>	Holds instances of R1 & R2. Waits for R3.
<b>P3</b>	Holds instance of R3.

# Resource allocation graph

- **Examples of resources of which there's a**
  - Single instance?
  - Multiple instances?
- **Assume we have  $n$  printers attached to a computer**
  - Do we need  $n$  instances of the same generic printer type?
  - Or  $n$  separate printer types?
  - Or something in between?

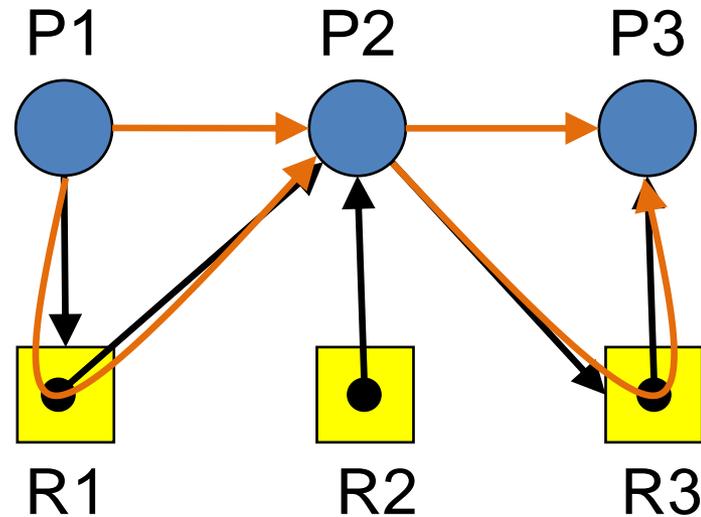
# Resource allocation graph

- Dining philosophers



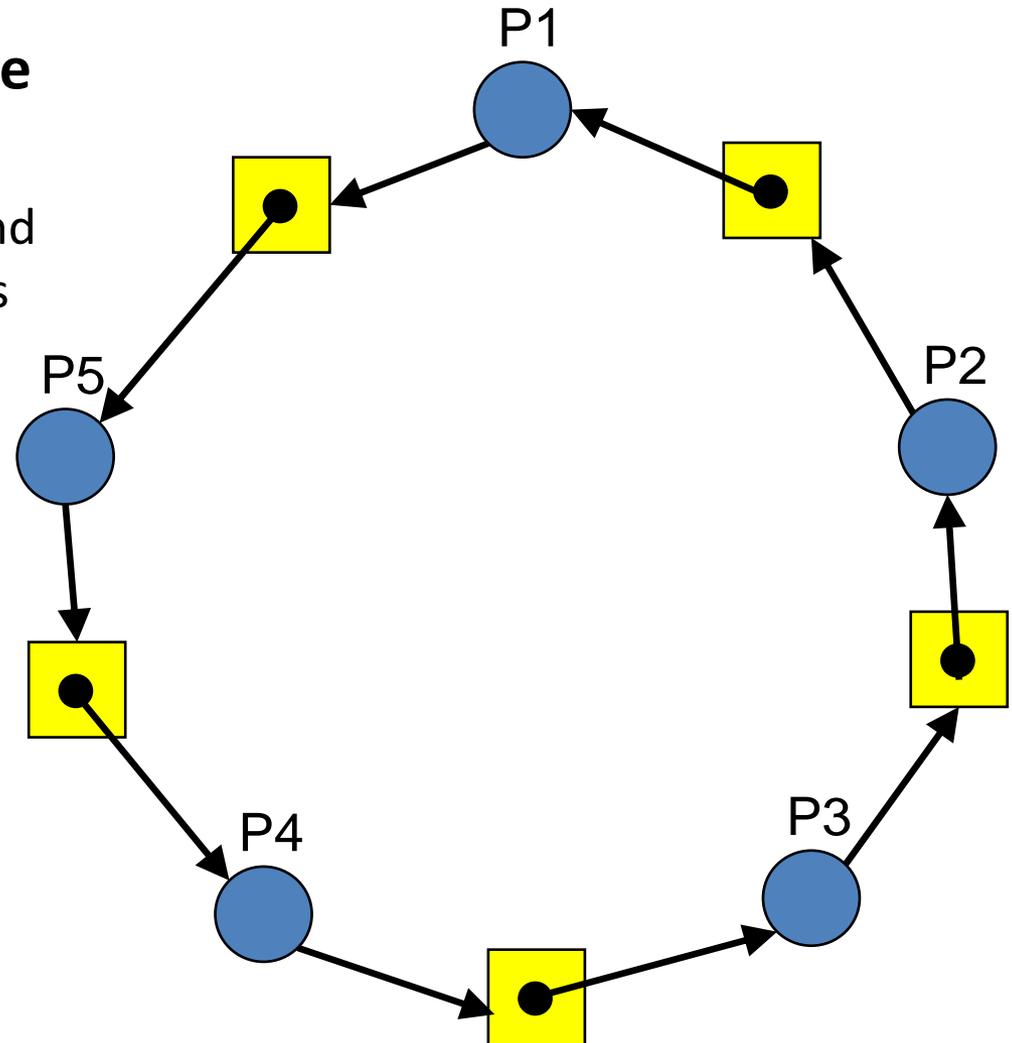
# Resource allocation graph

- **When there's only one instance per resource type**
  - Can simplify graph
  - By eliminating resources and only marking dependencies between processes



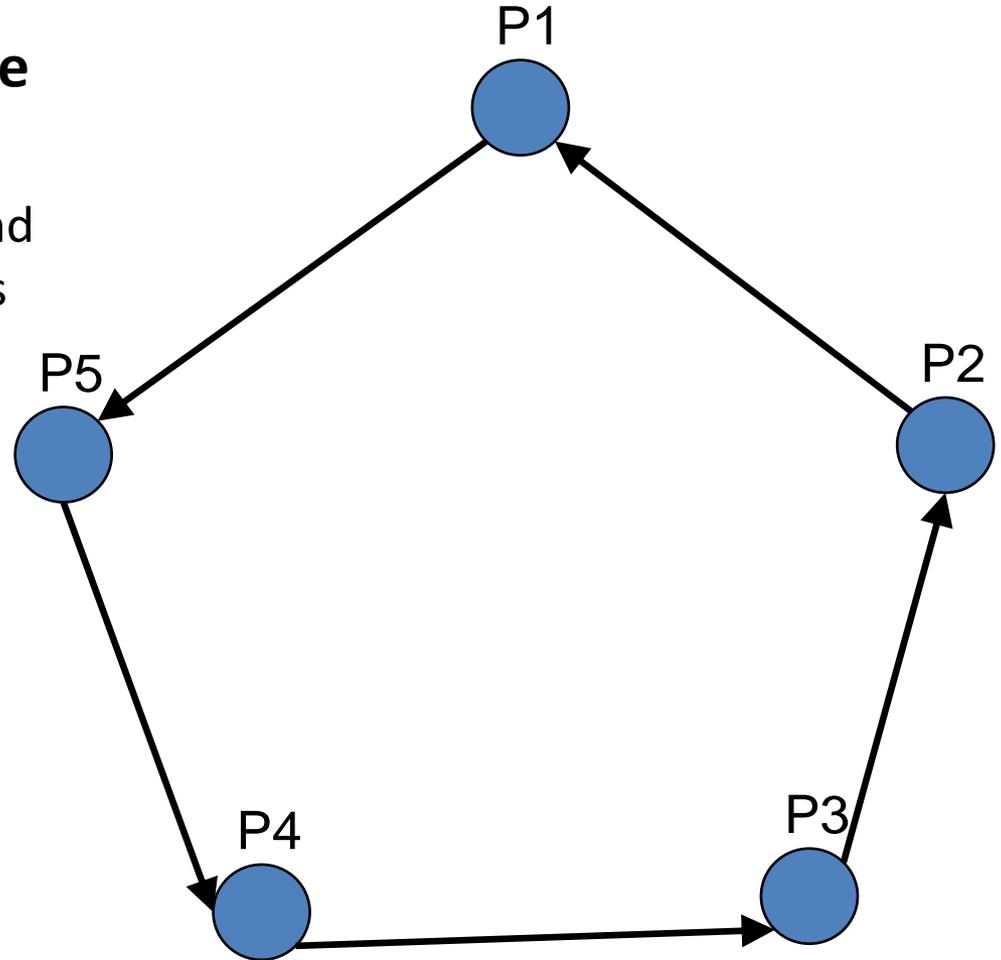
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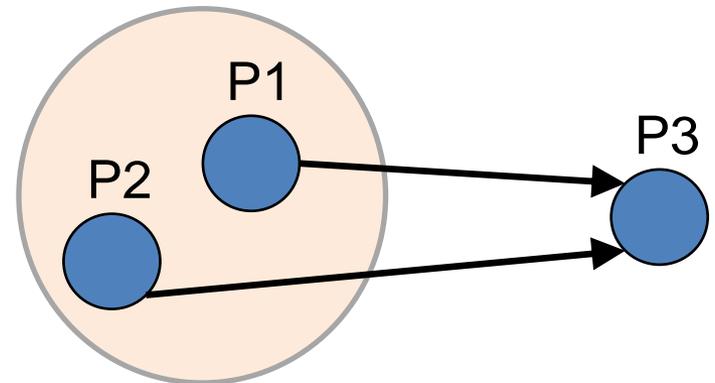
# Recall the formal definition of deadlock

- **Definition**

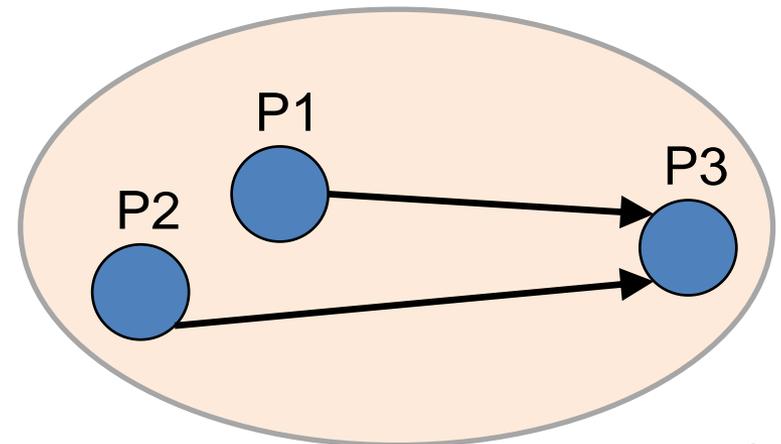
- A set of processes is deadlocked if each process in the set is waiting for a resource held by another process in the set

- **Why “in the set”?**

- No deadlock, even though every process in the set is waiting for a resource held by another process:

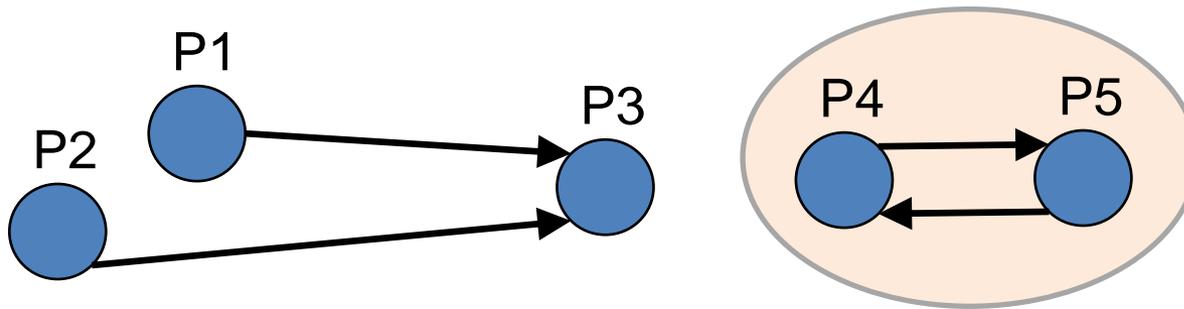


- Indeed, if including P3, then since P3 isn't waiting for a resource held by another process => no deadlock:



# Recall the formal definition of deadlock

- **Definition**
  - A set of processes is deadlocked if each process in the set is waiting for a resource held by another process in the set
- **Can the set be a subset?**
  - Of course



# Necessary conditions for deadlock

- **All of these *must* hold in order for a deadlock to occur**
  1. Mutual exclusion
    - Some resource is (i) used by more than one process, but is (ii) exclusively allocated to one process at a time, not shared
    - If used by only one process, or can be shared => can't deadlock
  2. Hold & wait
    - Processes may hold one resource and wait for another
    - If resources allocated atomically altogether => can't deadlock
  3. Circular wait
    - $P(i)$  waits for resource held by  $P((i+1) \% n)$
    - Otherwise, recursively, there exists one process that need not wait
  4. No resource preemption
    - If resources held can be released (e.g., after some period of time), then can break circular wait

# **DEALING WITH DEADLOCKS**

# Who's responsible?

- **Who is responsible for dealing with deadlocks?**
  - Typically you (the programmer)
  - The OS doesn't do it for you
  - You need to know how to do it and implement it yourself

# Can divide ways into 2

- 1. Design the system such that it is never allowed to enter into a deadlock situation**
  - Usable
- 2. Allow the system to experience deadlock, but put in mechanisms to detect & recover**
  - Less usable in practice

# Violate 1 of the 4 conditions

- **We've enumerated 4 conditions that must hold for deadlock to occur**
  - So violating any one of them will eliminate the possibility of deadlocking

# Violate “hold and wait”

- **Instead of acquiring resources one by one**
  - Each process requests all resources it'll need at the outset
  - System can then either provide all resources immediately
  - Or block process until all requested resources are available
- **Con**
  - Processes will hold on to their resources for more time than they actually need them
  - Limits concurrency and hence performance
- **Refinement**
  - Before a process issues a new (atomic) request for resources
  - It must release all resources it currently holds
    - (And of course, before that, bring system to consistent state)
  - Risking the resources will be allocated to other processes

# Violate “no resource preemption”

- **Under some circumstances, for some resources**
  - Can choose a victim process and release all its resources
  - For example, if there isn't enough memory, can write the victim's state to disk and release all its memory

# Violate “mutual exclusion”

- **It is possible to implement many canonical data structures (such as a linked list)**
  - Without using any form of explicit synchronization
    - No spinlocks, no semaphores, etc.
  - But while still allowing multiple threads to concurrently use of the data structure
- **How?**
  - Using HW-supported atomic operations only (such as test-and-set)
  - Such algorithms are (also) called “lock free”
    - Not to be confused with the “lock free” algorithm definition from a previous lecture (= “some thread always makes progress”)
- **Mature field**
  - Books on how to do it (formally proving implementations are correct)
  - Existing libraries to use without being exposed to the complexities

# Violate “circular wait”

- **Probably the most usable / practical / flexible way to prevent deadlocks**
  - (When lock-free data structures, that are getting popular, are unavailable)
- **How it’s done**
  - All resources are numbered in one sequence
    - $Ord(\text{printer})=1, Ord(\text{scanner})=2, Ord(\text{lock}_x)=3, Ord(\text{lock}_y)=4, \dots$
  - Processes must request resources in increasing  $Ord()$  order
  - Namely, a process holding some resources can only request additional resources that have strictly higher numbers
  - A process that wishes to acquire a resource that has a lower order
    - Must first release all the resources it currently holds

# Violate “circular wait”

- **Proof that it works**

- Assume by contradiction that there exists a cycle
- Without loss of generality, further assume that
  - $P(i)$  waits for  $P((i+1) \% n)$
- Let  $M(i)$  be
  - The maximal  $\text{Ord}()$  amongst the resources that  $P(i)$  holds
- Thus, since
  - Each  $P(i)$  acquires resources in order, and
  - $P(i)$  waits for a resource held by  $P((i+1) \% n)$
- Then
  - $M(i) < M((i+1) \% n)$   
=>  $M(0) < M(1) < M(2) < \dots < M(n) < M(0)$   
=>  $M(0) < M(0)$   
=> contradiction

# Violate “circular wait”

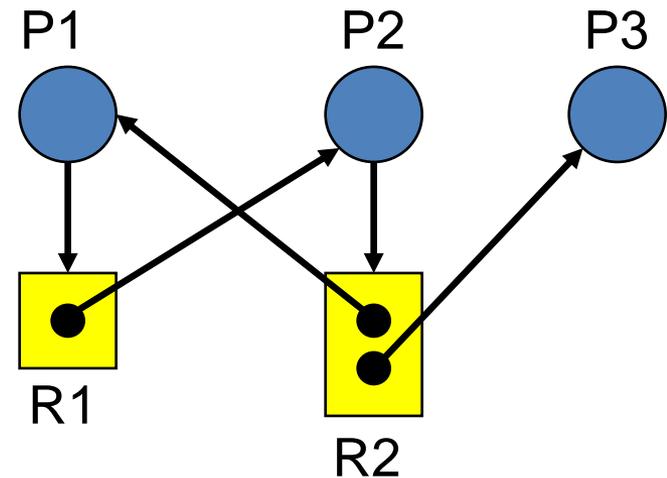
- **We number the chopsticks 0...4 and lock in order**

```
– if ( i < 4) // i can be 0...4
    wait( fork[i] )
    wait( fork[i+1] )
else // i==4
    wait( fork[0] ) // smaller
    wait( fork[4] ) // bigger

eat
signal( fork[i] )
signal( fork[(i+1) % 5] )
```

# Deadlock detection

- **If there's only one instance of each resource type**
  - Search for a cycle in the (simplified) resource allocation graph
    - Found  $\Leftrightarrow$  deadlock
- **In the general case, which allows multiple instances per type**
  - Necessary conditions for deadlock  $\neq$  sufficient conditions for deadlock
  - Indeed, a graph can have a cycle while the system is *not* deadlocked
  - Example.....
- **Can nevertheless detect deadlocks in general case**
  - But algorithm outside the scope of this course



# Recovery from a deadlock

- **After a deadlock has been detected (previous slide)**
  - Need to somehow recover
- **If possible, this is done by terminating some of the processes**
  - Until deadlock is resolved
  - Sometimes make sense, sometimes doesn't
- **Or, if possible, by preempting resources**
  - Of deadlocked processes
- **Finding a minimal (“optimal”) set of processes to terminate or resources to preempt is a hard problem**

# Deadlock avoidance

- **Rules**

- n processes
- k resource types (each type may have 1 or more instances)
- Upon initialization, each processes declares maximal number of resource-instances it'll need for each resource type
- While running, OS maintains how many resources are currently used by each process
- And how many resource instances per type are currently free

- **Upon process resource allocation request**

- OS will allocate only iff allocation isn't dangerous, namely
- It knows for a fact that it'll be able to avoid deadlock in the future
- Otherwise, the process will be blocked until a better time
- Algorithm is thus said to be conservative, as there's a possibility for no deadlock even if allocation is made, but OS doesn't take the chance

- **Upon process termination**

- Process releases all its resources

# Deadlock avoidance

- **Example**

- Banker's algorithm (by Dijkstra)
- Uses the notation of "safe state"
  - A state whereby we're sure that all processes can be executed, in a certain order, one after the other, such that each will obtain all the resources it needs to complete its execution
- By ensuring such a sequence exists after each allocation  
=> avoid deadlock

- **Banker's data structure**

- $\text{max}[p] = (m_1, m_2, \dots, m_k)$  = max resource requirements for process p
- $\text{cur}[p] = (c_1, c_2, \dots, c_k)$  = current resource allocation for process p
- $\text{avail} = (a_1, a_2, \dots, a_k)$  = currently free resources
- $R = (r_1, r_2, \dots, r_k)$  = the current resource request for process p

- **Example**

- $\text{max}[p] = (3,0,1)$ ,  $\text{cur}[p] = (3,0,0)$
- Note that  $\text{max}[p] \geq \text{cur}[p]$  always holds // compare by coordinates

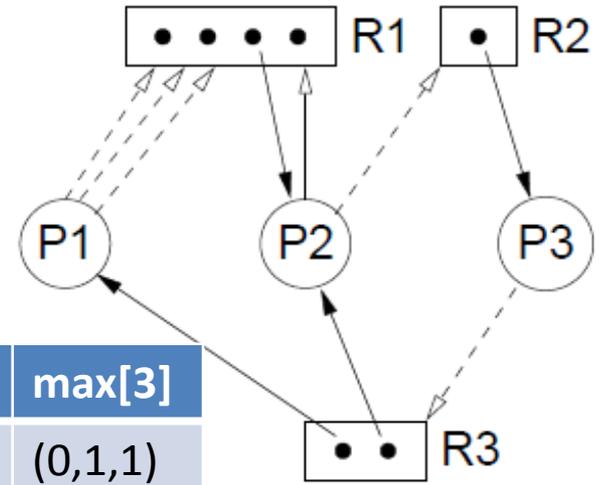
# Banker's algorithm

- **Tentatively assume that request R was granted**
  - `cur[p] += R` // vector addition
  - `avail -= R` // vector subtraction
- **Check if “safe state” (can satisfy all processes in some order)**
  - initialize P to hold all process
  - while( P isn't empty ) {
    - found = false
    - for each p in P { // find one p that can be satisfied
      - if(  $\text{max}[p] - \text{cur}[p] \leq \text{avail}$  ) // worst case for p
        - `avail += cur[p]` // “release” p's resources
        - `P -= {p}`
        - found = true
  - }
  - if( ! found ) return FAILURE
- }
- return SUCCESS

# Banker's algorithm – runtime complexity

- $O(n^2)$ 
  - Even though number of possible orders is  $n!$
  - Because resources increase monotonically as processes terminate,
  - As long as it's possible to execute any set of processes
    - Execution order not important
    - (There is never any need to backtrack and try another order)

# Banker's algorithm – example



- Initial system state

cur[1]	cur[2]	cur[3]	avail	max[1]	max[2]	max[3]
(0,0,1)	(1,0,1)	(0,1,0)	(3,0,0)	(3,0,1)	(2,1,1)	(0,1,1)

- P1 requires instance of R1 [R = (1,0,0)]

- Granting the request yields

cur[1]	cur[2]	cur[3]	avail	max[1]	max[2]	max[3]
(1,0,1)	(1,0,1)	(0,1,0)	(2,0,0)	(3,0,1)	(2,1,1)	(0,1,1)

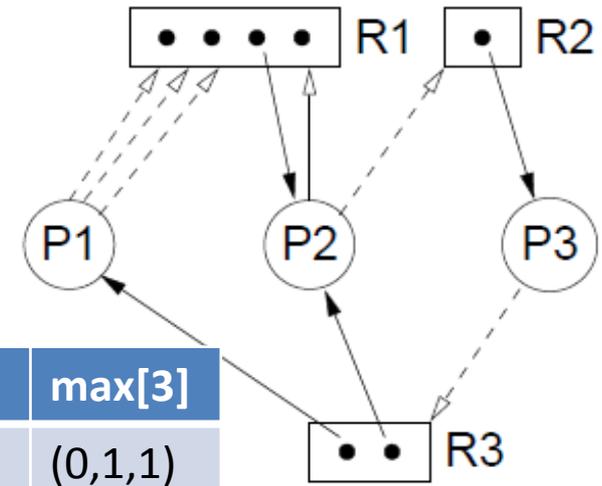
- Safe, because there are enough R1 instance so that P1's max additional request can be satisfied:  $\text{max}[1] - \text{cur}[1] = (2,0,0)$ ; so after P1's termination

	cur[2]	cur[3]	avail		max[2]	max[3]
	(1,0,1)	(0,1,0)	(3,0,1)		(2,1,1)	(0,1,1)

# Banker's algorithm – example

- Copied from previous slide

	cur[2]	cur[3]	avail		max[2]	max[3]
	(1,0,1)	(0,1,0)	(3,0,1)		(2,1,1)	(0,1,1)



- Not enough to satisfy P2 (why?), but can satisfy P3

–  $R3 = (0,1,1) - (0,1,0) = (0,0,1) (\leq \text{avail} = (3,0,1))$

	cur[2]	cur[3]	avail		max[2]	
	(1,0,1)		(3,1,1)		(2,1,1)	

# Ways to deal with deadlocks

## 1. Deadlock “prevention”

- Design system in which deadlock cannot happen
- Violate 1 of the 4

## 2. Deadlock “avoidance”

- System manages to stay away from deadlock situations by being careful on a per resource-allocation decision basis
- Banker’s

## 3. Deadlock detection & recovery

- Allow system to enter deadlock state, but put in place mechanisms that can detect, and recover from, this situation

**THANKS**